



---

# System Architecture Support Libraries (SASL)

Copyright © 1997-2021 Ericsson AB. All Rights Reserved.  
System Architecture Support Libraries (SASL) 4.1  
July 30, 2021

---

**Copyright © 1997-2021 Ericsson AB. All Rights Reserved.**

Licensed under the Apache License, Version 2.0 (the "License"); you may not use this file except in compliance with the License. You may obtain a copy of the License at <http://www.apache.org/licenses/LICENSE-2.0> Unless required by applicable law or agreed to in writing, software distributed under the License is distributed on an "AS IS" BASIS, WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either express or implied. See the License for the specific language governing permissions and limitations under the License. Ericsson AB. All Rights Reserved..

**July 30, 2021**

# 1 SASL User's Guide

---

The System Architecture Support Libraries SASL application provides support for alarm handling, release handling, and related functions.

## 1.1 Introduction

### 1.1.1 Scope

The SASL application provides support for:

- Error logging
- Alarm handling
- Release handling
- Report browsing

Section SASL Error Logging describes the error handler that produces the supervisor, progress, and crash reports, which can be written to screen or to a specified file. It also describes the Report Browser (RB).

The sections about release structure and release handling have been moved to section OTP Design Principles in **System Documentation**.

### 1.1.2 Prerequisites

It is assumed that the reader is familiar with the Erlang programming language.

## 1.2 SASL Error Logging

### Note:

The SASL error logging concept described in this section is deprecated since Erlang/OTP 21.0, when the new logging API was introduced.

The new default behaviour is that the SASL application no longer affects which log events that are logged. Supervisor reports and crash reports are logged via the default logger handler which is setup by Kernel. Progress reports are by default not logged, but can be enabled by setting the primary log level to `info`, for example by using the Kernel configuration parameter `logger_level`.

The old SASL error logging behaviour can be re-enabled by setting the Kernel configuration parameter `logger_sasl_compatible` to `true`.

The mechanism for multi-file error report logging as described in this section is also kept for backwards compatibility. However, the new logging API also introduces `logger_disk_log_h(3)`, which is a logger handler that can print to multiple files using `disk_log(3)`.

### 1.2.1 SASL reports

The SASL application introduces three types of reports:

- Supervisor report

- Progress report
- Crash report

When the SASL application is started, it adds a Logger handler that formats and writes these reports, as specified in the configuration parameters for SASL.

### Supervisor Report

A supervisor report is issued when a supervised child terminates unexpectedly. A supervisor report contains the following items:

Supervisor

Name of the reporting supervisor.

Context

Indicates in which phase the child terminated from the supervisor's point of view. This can be `start_error`, `child_terminated`, or `shutdown_error`.

Reason

Termination reason.

Offender

Start specification for the child.

### Progress Report

A progress report is issued when a supervisor starts or restarts a child. A progress report contains the following items:

Supervisor

Name of the reporting supervisor.

Started

Start specification for the successfully started child.

### Crash Report

Processes started with functions `proc_lib:spawn` or `proc_lib:spawn_link` are wrapped within a `catch`. A crash report is issued when such a process terminates with an unexpected reason, which is any reason other than `normal`, `shutdown`, or `{shutdown,Term}`. Processes using behaviors `gen_server`, `gen_fsm` or `gen_statem` are examples of such processes. A crash report contains the following items:

Crasher

Information about the crashing process, such as initial function call, exit reason, and message queue.

Neighbours

Information about processes that are linked to the crashing process and do not trap exits. These processes are the neighbours that terminate because of this process crash. The information gathered is the same as the information for Crasher, described in the previous item.

### Example

The following example shows the reports generated when a process crashes. The example process is a permanent process supervised by the `test_sup` supervisor. A division by zero is executed and the error is first reported by the faulty process. A crash report is generated, as the process was started using function `proc_lib:spawn/3`. The supervisor generates a supervisor report showing the crashed process. A progress report is generated when the process is finally restarted.

```

=ERROR REPORT==== 27-May-1996::13:38:56 ===
<0.63.0>: Divide by zero !

=CRASH REPORT==== 27-May-1996::13:38:56 ===
crasher:
pid: <0.63.0>
registered_name: []
error_info: {badarith,{test,s,[]}}
initial_call: {test,s,[]}
ancestors: [test_sup,<0.46.0>]
messages: []
links: [<0.47.0>]
dictionary: []
trap_exit: false
status: running
heap_size: 128
stack_size: 128
reductions: 348
neighbours:

=SUPERVISOR REPORT==== 27-May-1996::13:38:56 ===
Supervisor: {local,test_sup}
Context:    child_terminated
Reason:     {badarith,{test,s,[]}}
Offender:   [{pid,<0.63.0>},
             {name,test},
             {mfa,{test,t,[]}},
             {restart_type,permanent},
             {shutdown,200},
             {child_type,worker}]

=PROGRESS REPORT==== 27-May-1996::13:38:56 ===
Supervisor: {local,test_sup}
Started:    [{pid,<0.64.0>},
             {name,test},
             {mfa,{test,t,[]}},
             {restart_type,permanent},
             {shutdown,200},
             {child_type,worker}]

```

## 1.2.2 Multi-File Error Report Logging

Multi-file error report logging is used to store error messages received by `error_logger`. The error messages are stored in several files and each file is smaller than a specified number of kilobytes. No more than a specified number of files exist at the same time. The logging is very fast, as each error message is written as a binary term.

For more details, see the `sasl(6)` application in the Reference Manual.

## 1.2.3 Report Browser

The report browser is used to browse and format error reports written by the error logger handler `log_mf_h` defined in `STDLIB`.

The `log_mf_h` handler writes all reports to a report logging directory, which is specified when configuring the SASL application.

If the report browser is used offline, the reports can be copied to another directory specified when starting the browser. If no such directory is specified, the browser reads reports from the `SASL error_logger_mf_dir`.

### Starting Report Browser

Start the `rb_server` with function `rb:start([Options])` as shown in the following example:

```
5> rb:start([max, 20]).
rb: reading report...done.
rb: reading report...done.
rb: reading report...done.
rb: reading report...done.
{ok,<0.199.0>}
```

### Online Help

Enter command `rb:help()` to access the report browser online help system.

### List Reports in Server

Use function `rb:list()` to list all loaded reports:

```
4> rb:list().
No          Type          Process          Date          Time
==          ==          =====          ==          ==
20          progress        <0.17.0> 1996-10-16 16:14:54
19          progress        <0.14.0> 1996-10-16 16:14:55
18          error           <0.15.0> 1996-10-16 16:15:02
17          progress        <0.14.0> 1996-10-16 16:15:06
16          progress        <0.38.0> 1996-10-16 16:15:12
15          progress        <0.17.0> 1996-10-16 16:16:14
14          progress        <0.17.0> 1996-10-16 16:16:14
13          progress        <0.17.0> 1996-10-16 16:16:14
12          progress        <0.14.0> 1996-10-16 16:16:14
11          error           <0.17.0> 1996-10-16 16:16:21
10          error           <0.17.0> 1996-10-16 16:16:21
9           crash_report    release_handler 1996-10-16 16:16:21
8           supervisor_report <0.17.0> 1996-10-16 16:16:21
7           progress        <0.17.0> 1996-10-16 16:16:21
6           progress        <0.17.0> 1996-10-16 16:16:36
5           progress        <0.17.0> 1996-10-16 16:16:36
4           progress        <0.17.0> 1996-10-16 16:16:36
3           progress        <0.14.0> 1996-10-16 16:16:36
2           error           <0.15.0> 1996-10-16 16:17:04
1           progress        <0.14.0> 1996-10-16 16:17:09
ok
```

### Show Reports

Use function `rb:show(Number)` to show details of a specific report:

```

7> rb:show(4).

PROGRESS REPORT <0.20.0>                                1996-10-16 16:16:36
=====
supervisor                                           {local,sasl_sup}
started
[{pid,<0.24.0>},
 {name,release_handler},
 {mfa,{release_handler,start_link,[]}},
 {restart_type,permanent},
 {shutdown,2000},
 {child_type,worker}]

ok
8> rb:show(9).

CRASH REPORT <0.24.0>                                    1996-10-16 16:16:21
=====
Crashing process
pid                                                    <0.24.0>
registered_name                                         release_handler
error_info                                             {undef,{release_handler,mbj_func,[]}}
initial_call
{gen,init_it,
 [gen_server,
 <0.20.0>,
 <0.20.0>,
 {erlang,register},
 release_handler,
 release_handler,
 [],
 []]}
ancestors                                             [sasl_sup,<0.18.0>]
messages                                              []
links                                                  [<0.23.0>,<0.20.0>]
dictionary                                             []
trap_exit                                              false
status                                                  running
heap_size                                              610
stack_size                                             142
reductions                                             54

ok

```

## Search Reports

All reports containing a common pattern can be shown. Suppose a process crashes because it tries to call a non-existing function `release_handler:mbj_func/1`. The reports can then be shown as follows:

## 1.2 SASL Error Logging

---

```
12> rb:grep("mbj_func").
Found match in report number 11

ERROR REPORT <0.24.0>                                     1996-10-16 16:16:21
=====

** undefined function: release_handler:mbj_func[] **
Found match in report number 10

ERROR REPORT <0.24.0>                                     1996-10-16 16:16:21
=====

** Generic server release_handler terminating
** Last message in was {unpack_release,hej}
** When Server state == {state,[],
"/home/dup/otp2/otp_beam_sunos5_plg_7",
[{release,
"OTP APN 181 01",
"P1G",
undefined,
[],
permanent}],
undefined}
** Reason for termination ==
** {undef,{release_handler,mbj_func,[]}}
Found match in report number 9

CRASH REPORT <0.24.0>                                     1996-10-16 16:16:21
=====

Crashing process
pid                                     <0.24.0>
registered_name                       release_handler
error_info                           {undef,{release_handler,mbj_func,[]}}
initial_call
{gen,init_it,
[gen_server,
<0.20.0>,
<0.20.0>,
{erlang,register},
release_handler,
release_handler,
[],
[]]}
ancestors                             [sasl_sup,<0.18.0>]
messages                             []
links                                 [<0.23.0>,<0.20.0>]
dictionary                           []
trap_exit                             false
status                                running
heap_size                             610
stack_size                             142
reductions                             54

Found match in report number 8

SUPERVISOR REPORT <0.20.0>                                1996-10-16 16:16:21
=====

Reporting supervisor                    {local,sasl_sup}

Child process
errorContext                           child_terminated
reason                                 {undef,{release_handler,mbj_func,[]}}
pid                                     <0.24.0>
name                                    release_handler
```

```
start_function      {release_handler,start_link,[]}  
restart_type        permanent  
shutdown            2000  
child_type          worker  
  
ok
```

## Stop Server

Use function `rb:stop()` to stop the `rb_server`:

```
13> rb:stop().  
ok
```

# 2 Reference Manual

---

The SASL application provides support for alarm handling, release handling, and related functions.





`error_logger_mf_maxbytes = integer()`

Specifies the maximum size of each individual file written by `log_mf_h`. If this parameter is undefined, the `log_mf_h` handler is not installed.

`error_logger_mf_maxfiles = 0<integer()<256`

Specifies the number of files used by `log_mf_h`. If this parameter is undefined, the `log_mf_h` handler is not installed.

The new `logger_disk_log_h` might be an alternative to `log_mf_h` if log rotation is desired. This does, however, write the log events in clear text and not as binaries.

## See Also

`alarm_handler(3)`, `error_logger(3)`, `logger(3)`, `log_mf_h(3)`, `rb(3)`, `release_handler(3)`, `systools(3)`



## See Also

`error_logger(3)`, `gen_event(3)`







**stop()**

Stops `rb_server`.

**stop\_log()**

Closes the log file. The output from the RB tool is directed to `standard_io`.









**Note:**

Installing a new release can be time consuming if there are many processes in the system. The reason is that each process must be checked for references to old code before a module can be purged. This check can lead to garbage collections and copying of data.

To speed up the execution of `install_release`, first call `check_install_release`, using option `purge`. This does the same check for old code. Then purges all modules that can be soft-purged. The purged modules do then no longer have any old code, and `install_release` does not need to do the checks.

This does not reduce the overall time for the upgrade, but it allows checks and purge to be executed in the background before the real upgrade is started.

**Note:**

When upgrading the emulator from a version older than OTP R15, an attempt is made to load new application beam code into the old emulator. Sometimes the new beam format cannot be read by the old emulator, so the code loading fails and the complete upgrade is terminated. To overcome this problem, the new application code is to be compiled with the old emulator. For more information about emulator upgrade from pre OTP R15 versions, see Design Principles in **System Documentation**.

```
make_permanent(Vsn) -> ok | {error, Reason}
```

Types:

```
Vsn = string()  
Reason = {bad_status, Status} | term()
```

Makes the specified release version `Vsn` permanent.

```
remove_release(Vsn) -> ok | {error, Reason}
```

Types:

```
Vsn = string()  
Reason = {permanent, Vsn} | client_node | term()
```

Removes a release and its files from the system. The release must not be the permanent release. Removes only the files and directories not in use by another release.

```
reboot_old_release(Vsn) -> ok | {error, Reason}
```

Types:

```
Vsn = string()  
Reason = {bad_status, Status} | term()
```

Reboots the system by making the old release permanent, and calls `init:reboot()` directly. The release must have status `old`.

```
set_removed(Vsn) -> ok | {error, Reason}
```

Types:

```
Vsn = string()  
Reason = {permanent, Vsn} | term()
```

Makes it possible to handle removal of releases outside the release handler. Tells the release handler that the release is removed from the system. This function does not delete any files.

```
set_unpacked(RelFile, AppDirs) -> {ok, Vsn} | {error, Reason}
```

Types:

```
RelFile = string()
AppDirs = [{App, Vsn, Dir}]
App = atom()
Vsn = Dir = string()
Reason = term()
```

Makes it possible to handle unpacking of releases outside the release handler. Tells the release handler that the release is unpacked. Vsn is extracted from the release resource file RelFile.

AppDirs can be used to specify from where the modules for the specified applications are to be loaded. App is the name of an application, Vsn is the version, and Dir is the name of the directory where App-Vsn is located. The corresponding modules are to be located under Dir/App-Vsn/ebin. The directories for applications not specified in AppDirs are assumed to be located in \$ROOT/lib.

```
unpack_release(Name) -> {ok, Vsn} | {error, Reason}
```

Types:

```
Name = Vsn = string()
Reason = client_node | term()
```

Unpacks a release package Name.tar.gz located in the releases directory.

Performs some checks on the package, for example, checks that all mandatory files are present, and extracts its contents.

```
which_releases() -> [{Name, Vsn, Apps, Status}]
```

Types:

```
Name = Vsn = string()
Apps = ["App-Vsn"]
Status = unpacked | current | permanent | old
```

Returns all releases known to the release handler.

```
which_releases(Status) -> [{Name, Vsn, Apps, Status}]
```

Types:

```
Name = Vsn = string()
Apps = ["App-Vsn"]
Status = unpacked | current | permanent | old
```

Returns all releases, known to the release handler, of a specific status.

The following functions can be used to test upgrade and downgrade of single applications (instead of upgrading/downgrading an entire release). A script corresponding to the instructions in the relup file is created on-the-fly, based on the .appup file for the application, and evaluated exactly in the same way as release\_handler does.

**Warning:**

These functions are primarily intended for simplified testing of .appup files. They are not run within the context of the release\_handler process. They must therefore **not** be used together with calls to install\_release/1,2, as this causes the release\_handler to end up in an inconsistent state.

No persistent information is updated, so these functions can be used on any Erlang node, embedded or not. Also, using these functions does not affect which code is loaded if there is a reboot.

If the upgrade or downgrade fails, the application can end up in an inconsistent state.

## Exports

upgrade\_app(App, Dir) -> {ok, Unpurged} | restart\_emulator | {error, Reason}

Types:

```
App = atom()
Dir = string()
Unpurged = [Module]
Module = atom()
Reason = term()
```

Upgrades an application App from the current version to a new version located in Dir according to the .appup file.

App is the name of the application, which must be started. Dir is the new library directory of App. The corresponding modules as well as the .app and .appup files are to be located under Dir/ebin.

The function looks in the .appup file and tries to find an upgrade script from the current version of the application using upgrade\_script/2. This script is evaluated using eval\_appup\_script/4, exactly in the same way as install\_release/1,2 does.

Returns one of the following:

- {ok, Unpurged} if evaluating the script is successful, where Unpurged is a list of unpurged modules
- restart\_emulator if this instruction is encountered in the script
- {error, Reason} if an error occurred when finding or evaluating the script

If the restart\_new\_emulator instruction is found in the script, upgrade\_app/2 returns {error, restart\_new\_emulator}. This because restart\_new\_emulator requires a new version of the emulator to be started before the rest of the upgrade instructions can be executed, and this can only be done by install\_release/1,2.

downgrade\_app(App, Dir) ->

downgrade\_app(App, OldVsn, Dir) -> {ok, Unpurged} | restart\_emulator | {error, Reason}

Types:

```
App = atom()
Dir = OldVsn = string()
Unpurged = [Module]
Module = atom()
Reason = term()
```





`{cannot_extract_file, Name, Reason}`

Problems when extracting from a tar file, `erl_tar:extract/2` returned `{error, {Name, Reason}}`.

`{existing_release, Vsn}`

Specified release version `Vsn` is already in use.

`{Master, Reason, When}`

Some operation, indicated by the term `When`, failed on the master node `Master` with the specified error reason `Reason`.

`{no_matching_relop, Vsn, CurrentVsn}`

Cannot find a script for upgrading/downgrading between `CurrentVsn` and `Vsn`.

`{no_such_directory, Path}`

The directory `Path` does not exist.

`{no_such_file, Path}`

The path `Path` (file or directory) does not exist.

`{no_such_file, {Master, Path}}`

The path `Path` (file or directory) does not exist at the master node `Master`.

`{no_such_release, Vsn}`

The specified release version `Vsn` does not exist.

`{not_a_directory, Path}`

`Path` exists but is not a directory.

`{Posix, File}`

Some file operation failed for `File`. `Posix` is an atom named from the Posix error codes, such as `ENOENT`, `EACCES`, or `EISDIR`. See `file(3)` in Kernel.

`Posix`

Some file operation failed, as for the previous item in the list.

## See Also

OTP Design Principles, `config(4)`, `rel(4)`, `relup(4)`, `script(4)`, `sys(3)`, `systools(3)`

## systools

---

Erlang module

This module contains functions to generate boot scripts (`.boot`, `.script`), a release upgrade file (`relup`), and release packages.

### Exports

```
make_relup(Name, UpFrom, DownTo) -> Result  
make_relup(Name, UpFrom, DownTo, [Opt]) -> Result
```

Types:

```
Name = string()  
UpFrom = DownTo = [Name | {Name,Descr}]  
Descr = term()  
Opt = {path,[Dir]} | restart_emulator | silent | noexec | {outdir,Dir} |  
warnings_as_errors  
Dir = string()  
Result = ok | error | {ok,Relup,Module,Warnings} | {error,Module,Error}  
Relup, see relup(4)  
Module = atom()  
Warnings = Error = term()
```

Generates a release upgrade file `relup` containing instructions for upgrading from or downgrading to one or more previous releases. The instructions are used by `release_handler` when installing a new version of a release in runtime.

By default, `relup` file is located in the current working directory. If option `{outdir,Dir}` is specified, the `relup` file is located in `Dir` instead.

The release resource file `Name.rel` is compared with all release resource files `Name2.rel`, specified in `UpFrom` and `DownTo`. For each such pair, the following is deducted:

- Which applications to be deleted, that is, applications listed in `Name.rel` but not in `Name2.rel`
- Which applications to be added, that is, applications listed in `Name2.rel` but not in `Name.rel`
- Which applications to be upgraded/downgraded, that is, applications listed in both `Name.rel` and `Name2.rel` but with different versions
- If the emulator needs to be restarted after upgrading or downgrading, that is, if the ERTS version differs between `Name.rel` and `Name2.rel`

Instructions for this are added to the `relup` file in the above order. Instructions for upgrading or downgrading between application versions are fetched from the relevant application upgrade files `App.appup`, sorted in the same order as when generating a boot script, see `make_script/1,2`. High-level instructions are translated into low-level instructions and the result is printed to the `relup` file.

The optional `Descr` parameter is included "as is" in the `relup` file, see `relup(4)`. Defaults to the empty list.

All the files are searched for in the code path. It is assumed that the `.app` and `.appup` files for an application are located in the same directory.

If option `{path,[Dir]}` is specified, this path is appended to the current path. Wildcard `*` is expanded to all matching directories, for example, `lib/*/ebin`.







### include

Each separate (variable) package is included in the main `ReleaseName.tar.gz` file. This is the default.

### ownfile

Each separate (variable) package is generated as a separate file in the same directory as the `ReleaseName.tar.gz` file.

### omit

No separate (variable) packages are generated. Applications that are found underneath a variable directory are ignored.

A directory `releases` is also included in the release package, containing `Name.rel` and a subdirectory `RelVsn`. `RelVsn` is the release version as specified in `Name.rel`.

`releases/RelVsn` contains the boot script `Name.boot` renamed to `start.boot` and, if found, the files `relup` and `sys.config` or `sys.config.src`. These files are searched for in the same directory as `Name.rel`, in the current working directory, and in any directories specified using option `path`. In the case of `sys.config` it is not included if `sys.config.src` is found.

If the release package is to contain a new Erlang runtime system, the `erts-ErtsVsn/bin` directory of the specified runtime system `{erts,Dir}` is copied to `erts-ErtsVsn/bin`. Some erts executables are not copied by default, if you want to include all executables you can give the `erts_all` option.

All checks with function `make_script` are performed before the release package is created. Options `src_tests` and `exref` are also valid here.

The return value and the handling of errors and warnings are the same as described for `make_script`.

`script2boot(File) -> ok | error`

Types:

**File = string()**

The Erlang runtime system requires that the contents of the script used to boot the system is a binary Erlang term. This function transforms the `File.script` boot script to a binary term, which is stored in the `File.boot` file.

A boot script generated using `make_script` is already transformed to the binary form.

## See Also

`app(4)`, `appup(4)`, `erl(1)`, `rel(4)`, `release_handler(3)`, `relup(4)`, `script(4)`







```
{restart_application, Application}
  Application = atom()
```

Restarting an application means that the application is stopped and then started again, similar to using the instructions `remove_application` and `add_application` in sequence. Note that, even if the application has been started before the release upgrade is performed, `restart_application` may only load it rather than start it, depending on the application's `start_type`: If `Type = load`, the application is only loaded. If `Type = none`, the application is not loaded and not started, although the code for its modules is loaded.

## Low-Level Instructions

```
{load_object_code, {App, Vsn, [Mod]}}
  App = Mod = atom()
  Vsn = string()
```

Reads each `Mod` from directory `App-Vsn/ebin` as a binary. It does not load the modules. The instruction is to be placed first in the script to read all new code from the file to make the suspend-load-resume cycle less time-consuming.

```
point_of_no_return
```

If a crash occurs after this instruction, the system cannot recover and is restarted from the old release version. The instruction must only occur once in a script. It is to be placed after all `load_object_code` instructions.

```
{load, {Mod, PrePurge, PostPurge}}
  Mod = atom()
  PrePurge = PostPurge = soft_purge | brutal_purge
```

Before this instruction occurs, `Mod` must have been loaded using `load_object_code`. This instruction loads the module. `PrePurge` is ignored. For a description of `PostPurge`, see the high-level instruction update earlier.

```
{remove, {Mod, PrePurge, PostPurge}}
  Mod = atom()
  PrePurge = PostPurge = soft_purge | brutal_purge
```

Makes the current version of `Mod` old. `PrePurge` is ignored. For a description of `PostPurge`, see the high-level instruction update earlier.

```
{purge, [Mod]}
  Mod = atom()
```

Purges each module `Mod`, that is, removes the old code. Notice that any process executing purged code is killed.

```
{suspend, [Mod | {Mod, Timeout}]}
  Mod = atom()
  Timeout = int()>0 | default | infinity
```

Tries to suspend all processes using a module `Mod`. If a process does not respond, it is ignored. This can cause the process to die, either because it crashes when it spontaneously switches to new code, or as a result of a purge operation. If no `Timeout` is specified or `default` is specified, the default value for `sys:suspend` is used.

```
{resume, [Mod]}
  Mod = atom()
```

Resumes all suspended processes using a module `Mod`.

```
{code_change, [{Mod, Extra}]}
{code_change, Mode, [{Mod, Extra}]}
  Mod = atom()
  Mode = up | down
  Extra = term()
```

Mode defaults to `up` and specifies if it is an upgrade or downgrade. This instruction sends a `code_change` system message to all processes using a module `Mod` by calling function `sys:change_code`, passing term `Extra` as argument.

```
{stop, [Mod]}
  Mod = atom()
```

Stops all processes using a module `Mod` by calling `supervisor:terminate_child/2`. This instruction is useful when the simplest way to change code is to stop and restart the processes that run the code.

```
{start, [Mod]}
  Mod = atom()
```

Starts all stopped processes using a module `Mod` by calling `supervisor:restart_child/2`.

```
{sync_nodes, Id, [Node]}
{sync_nodes, Id, {M, F, A}}
  Id = term()
  Node = node()
  M = F = atom()
  A = [term()]
```

`apply(M, F, A)` must return a list of nodes.

This instruction synchronizes the release installation with other nodes. Each `Node` must evaluate this command with the same `Id`. The local node waits for all other nodes to evaluate the instruction before execution continues. If a node goes down, it is considered to be an unrecoverable error, and the local node is restarted from the old release. There is no time-out for this instruction, which means that it can hang forever.

```
{apply, {M, F, A}}
  M = F = atom()
  A = [term()]
```

Evaluates `apply(M, F, A)`.

If the instruction appears before instruction `point_of_no_return`, a failure is caught. `release_handler:install_release/1` then returns `{error, {'EXIT', Reason}}`, unless `{error, Error}` is thrown or returned. Then it returns `{error, Error}`.

If the instruction appears after instruction `point_of_no_return` and the function call fails, the system is restarted.

```
restart_new_emulator
```

This instruction is used when the application ERTS, Kernel, STDLIB, or SASL is upgraded. It shuts down the current emulator and starts a new one. All processes are terminated gracefully, and the new version of ERTS, Kernel, STDLIB, and SASL are used when the emulator restarts. Only one `restart_new_emulator` instruction is allowed in

the `relup` file, and it must be placed first. `systools:make_relup/3,4` ensures this when the `relup` file is generated. The rest of the instructions in the `relup` file is executed after the restart as a part of the boot script.

An info report is written when the upgrade is completed. To programmatically determine if the upgrade is complete, call `release_handler:which_releases/0,1` and check if the expected release has status `current`.

The new release must still be made permanent after the upgrade is completed, otherwise the old emulator is started if there is an emulator restart.

### Warning:

As stated earlier, instruction `restart_new_emulator` causes the emulator to be restarted with new versions of ERTS®, Kernel, STDLIB, and SASL. However, all other applications do at startup run their old versions in this new emulator. This is usually no problem, but every now and then incompatible changes occur to the core applications, which can cause trouble in this setting. Such incompatible changes (when functions are removed) are normally preceded by a deprecation over two major releases. To ensure that your application is not crashed by an incompatible change, always remove any call to deprecated functions as soon as possible.

```
restart_emulator
```

This instruction is similar to `restart_new_emulator`, except it must be placed at the end of the `relup` file. It is not related to an upgrade of the emulator or the core applications, but can be used by any application when a complete reboot of the system is required.

When generating the `relup` file, `systools:make_relup/3,4` ensures that there is only one `restart_emulator` instruction and that it is the last instruction in the `relup` file.

## See Also

```
release_handler(3), relup(4), supervisor(3), systools(3)
```



**Note:**

The list of applications must contain the Kernel and STDLIB applications.

## See Also

`application(3)`, `relup(4)`, `systools(3)`

---

## relup

---

Name

The **release upgrade file** describes how a release is upgraded in a running system.

This file is automatically generated by `systools:make_relup/3,4`, using a release resource file (`.rel`), application resource files (`.app`), and application upgrade files (`.appup`) as input.

## File Syntax

In a target system, the release upgrade file is to be located in directory `$ROOT/releases/Vsn`.

The `relup` file contains one single Erlang term, which defines the instructions used to upgrade the release. The file has the following syntax:

```
{Vsn,  
 [{UpFromVsn, Descr, Instructions}, ...],  
 [{DownToVsn, Descr, Instructions}, ...]}.
```

`Vsn = string()`

Current release version.

`UpFromVsn = string()`

Earlier version of the release to upgrade from.

`Descr = term()`

A user-defined parameter passed from the function `systools:make_relup/3,4`. It is used in the return value of `release_handler:install_release/1,2`.

`Instructions`

A list of low-level release upgrade instructions, see `appup(4)`. It consists of the release upgrade instructions from the respective application upgrade files (high-level instructions are translated to low-level instructions), in the same order as in the start script.

`DownToVsn = string()`

Earlier version of the release to downgrade to.

## See Also

`app(4)`, `appup(4)`, `rel(4)`, `release_handler(3)`, `systools(3)`

## script

---

Name

The **boot script** describes how the Erlang runtime system is started. It contains instructions on which code to load and which processes and applications to start.

Command `erl -boot Name` starts the system with a boot file called `Name.boot`, which is generated from the `Name.script` file, using `systools:script2boot/1`.

The `.script` file is generated by `systools` from a `.rel` file and from `.app` files.

## File Syntax

The boot script is stored in a file with extension `.script`. The file has the following syntax:

```
{script, {Name, Vsn},
 [
  {progress, loading},
  {preLoaded, [Mod1, Mod2, ...]},
  {path, [Dir1, "$ROOT/Dir", ...]},
  {primLoad, [Mod1, Mod2, ...]},
  ...
  {kernel_load_completed},
  {progress, loaded},
  {kernelProcess, Name, {Mod, Func, Args}},
  ...
  {apply, {Mod, Func, Args}},
  ...
  {progress, started}}].
```

`Name = string()`

Defines the system name.

`Vsn = string()`

Defines the system version.

`{progress, Term}`

Sets the "progress" of the initialization program. The `init:get_status/0` function returns the current value of the progress, which is `{InternalStatus, Term}`.

`{path, [Dir]}`

`Dir` is a string. This argument sets the load path of the system to `[Dir]`. The load path used to load modules is obtained from the initial load path, which is given in the script file, together with any path flags that were supplied in the command-line arguments. The command-line arguments modify the path as follows:

- `-pa Dir1 Dir2 ... DirN` adds the directories `DirN`, `DirN-1`, ..., `Dir2`, `Dir1` to the front of the initial load path.
- `-pz Dir1 Dir2 ... DirN` adds the directories `Dir1`, `Dir2`, ..., `DirN` to the end of the initial load path.
- `-path Dir1 Dir2 ... DirN` defines a set of directories `Dir1`, `Dir2`, ..., `DirN`, which replace the search path given in the script file. Directory names in the path are interpreted as follows:
  - Directory names starting with `/` are assumed to be absolute path names.
  - Directory names not starting with `/` are assumed to be relative the current working directory.

- The special `$ROOT` variable can only be used in the script, not as a command-line argument. The given directory is relative the Erlang installation directory.

```
{primLoad, [Mod]}
```

Loads the modules `[Mod]` from the directories specified in `Path`. The script interpreter fetches the appropriate module by calling `erl_prim_loader:get_file(Mod)`. A fatal error that terminates the system occurs if the module cannot be located.

```
{kernel_load_completed}
```

Indicates that all modules that **must** be loaded **before** any processes are started are loaded. In interactive mode, all `{primLoad, [Mod]}` commands interpreted after this command are ignored, and these modules are loaded on demand. In embedded mode, `kernel_load_completed` is ignored, and all modules are loaded during system start.

```
{kernelProcess, Name, {Mod, Func, Args}}
```

Starts the "kernel process" `Name` by evaluating `apply(Mod, Func, Args)`. The start function is to return `{ok, Pid}` or `ignore`. The `init` process monitors the behavior of `Pid` and terminates the system if `Pid` dies. Kernel processes are key components of the runtime system. Users do not normally add new kernel processes.

```
{apply, {Mod, Func, Args}}.
```

The `init` process evaluates `apply(Mod, Func, Args)`. The system terminates if this results in an error. The boot procedure hangs if this function never returns.

### Note:

In an interactive system, the code loader provides demand-driven code loading, but in an embedded system the code loader loads all code immediately. The same version of code is used in both cases. The code server calls `init:get_argument(mode)` to determine if it is to run in demand mode or non-demand driven mode.

## See Also

`systools(3)`